Instruction Set > CIP Axis Attributes > Motion Control Interface Attributes

# Motion Control Interface Attributes

The Motion Control Interface attributes are used by the Logix Designer application to support the interface to an axis. Interface attributes are used to customize what choices appear on the properties pages and help you structure a motion axis.

**Tip:** Remember that the attributes that appear in the Logix Designer application are dependent on the current Control Mode.

### **Axis Address**

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - All	Get	DINT	-	-	-	Absolute Address

Absolute Address of Motion Control Axis Object data structure. The Axis Address attribute is used to return the actual physical address in memory where the axis instance is located.

### **Axis Instance**

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - All	Get/ GSV	DINT	-	-	-	Instance Number

Instance Number assigned to this instance of the Motion Control Axis Object. The Axis Instance attribute is used to return the instance number of an axis. An example of using this attribute is responding to an axis major fault. Major fault records contain the axis instance of the offending axis. Use this attribute to query an axis instance and determine if the instance number matches the fault record.

The Axis Instance attribute is required when accessing an attribute using a MSG instruction.

# **Group Instance**

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - All	Get/ GSV	DINT	-	-	-	Instance Number

Instance Number of the Motion Group assigned to this instance of the Motion Control Axis Object. Use the Group Instance attribute to determine what motion group this axis is assigned to.

# Map Instance

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - All	Set/ GSV	DINT	-	-	-	Instance Number

I/O Map Instance Number assigned to this instance of the Motion Control Axis Object. The Map Instance attribute associates an axis to a specific motion compatible module by specifying the I/O map entry representing the module. This value is set to 0 for virtual and consumed data types.

#### Search



- **Quick Start Steps**
- ▶ <u>Logix Designer</u>
- ▶ Module Information
- ▲ Instruction Set

Logix 5000 Controllers **Instruction and Application Considerations** 

**Logix Designer Application** <u>Instruction Set</u>

**Interpret the Attribute Tables** 

<u>Array Concepts</u>

- ▲ CIP Axis Attributes AXIS\_CIP\_DRIVE Diagrams **AXIS CIP DRIVE Structure** 
  - Accessing Attributes **AC Line Condition Attributes Acceleration Control Attributes Acceleration Control Configuration Attributes Additional Error Code** <u>Information</u>
  - ▶ APR Fault Attributes **Auto-Tune Configuration Attributes**
  - Axis Exception Action **Configuration Attributes Axis Info Attributes Axis Safety Status Attributes Axis Statistical Attributes CIP Axis Status Attributes CIP Error Codes CIP Motion Axis Control Modes**
  - **Generation Attributes Configuration Fault Attributes Control Mode Attributes** Converter AC Line **Configuration Attributes Converter AC Line Monitoring Attributes** Converter AC Line Source **Configuration Attributes** Converter Bus Voltage **Control Configuration** <u>Attributes</u>

Converter Bus Voltage

**Control Signal Attributes** 

Converter Control Mode

Attributos

### Module Channel

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - All	Set/ GSV	USINT	255	-	-	Channel Number (0, 1, 2,) A value of 255 indicates the axis is unassigned.

Channel number of the module assigned to this instance of the Motion Control Axis Object. The Module Channel attribute associates an axis to a specific channel on a motion compatible module by specifying the Module Channel attribute.

### Module Class Code

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - All	Set/ GSV	DINT	-	-	1	Object Class Code

Object class code of the motion engine in the module. The Module Class Code attribute is the class code of the object in the motion module which is supporting motion; for example 0xAF is the object ID of the Servo Module Axis residing in the 1756-M02AE module.

# C2C Map Instance

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - All	Set/ GSV	DINT	-	-	-	Producer/Consumed axis's associated C2C map instance

Producer/Consumed axis's associated C2C map instance. When the Axis Data Type attribute is specified to be 'Consumed' then this axis is associated to the consumed data by specifying both the C2C Map Instance and the C2C Connection Instance. For all other Axis Data Types if this axis is to be produced then this attribute is set to 1 (one) to indicate that the connection is off of the local controller's map instance.

### **C2C Connection Instance**

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - All	Set/ GSV	DINT	-	-	-	Producer/Consumed axis's associated C2C connection in reference to the C2C map instance

Producer/Consumed axis's associated C2C connection in reference to the C2C map instance. If this axis is to be produced, then this attribute is set to the connection instance under the local controller's map instance (1) that will be used to send the remote axis data through the C2C connection.

# Memory Use

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
-------	--------	--------------	---------	-----	-----	---------------------

#### <u>ALLI IDULES</u>

Converter Current Control

**Configuration Attributes** 

**Converter Current Control** 

<u>Signal Attributes</u>

**Converter Current** 

**Reference Configuration** 

<u>Attributes</u>

**Converter Current** 

Reference Signal Attributes

**Converter Output** 

**Attributes** 

**Converter Reactive Power** 

**Control Attributes** 

Converter Types

<u>Current Control Signal</u>

**Attributes** 

**Current Control** 

**Configuration Attributes** 

Cyclic Read and Cyclic Write

**DC Bus Condition** 

**Attributes** 

**Device Function Codes** 

**Device Commissioning** 

<u>Attributes</u>

<u>Drive General Purpose I/O</u>

<u>Attributes</u>

**Drive Output Attributes** 

**Drive Parameters** 

**Event Capture Attributes** 

**Exception Factory Limit** 

**Info Attributes** 

**Exception User Limit** 

**Configuration Attributes** 

Exception, Fault and Alarm

<u>Attributes</u>

<u>Exceptions</u>

Fault and Alarm Behavior

Feedback Interface Types

**Feedback Configuration** 

<u>Attributes</u>

**Frequency Control** 

**Configuration Attributes** 

Frequency Control Signal

<u>Attribute</u>

<u>General Feedback Info</u>

**Attributes** 

**General Feedback Signal** 

**Attributes** 

**General Linear Motor** 

**Attributes** 

**General Motor Attributes** 

**General Permanent** 

**Magnet Motor Attributes** 

**General Rotary Motor** 

Required - All	Get/ GSV	UINT	-	-	-	105 (0x69) = I/O space
All	GSV					106 (0x6a) = Data Table space
						space

Controller memory space where this instance of the Motion Control Axis Object exists. This attribute is initialized as part of the create service when you create the axis.

The Logix Designer programming application uses this attribute to create axis instances in I/O memory for axes that are either to be produced or consumed.

The Memory Use attribute can only be set as part of an axis create service and is used to control which controller memory the object instance is created in.

# Memory Usage

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - All	Get	DINT	-	-	-	Bytes

Amount of memory consumed for this instance of the Motion Control Axis Object. The Memory Use attribute can be used to determine the amount of memory the created instance consumes in bytes.

# Axis Data Type

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - All	Get	USINT	-	-	-	Enumeration:
						0 = Feedback
						1 = Consumed
						2 = Virtual
						3 = Generic
						4 = Servo
						5 = Servo Drive
						6 = Generic Drive
						7 = CIP Drive

Associated tag data type for this instance of the Motion Control Axis Object. This attribute is initialized as part of the create service when you create the axis.

The Axis Data Type attribute and is used to determine which data template, memory format, and set of attributes are created and applicable for this axis instance. This attribute can only be set as part of an axis create service.

# **Axis Configuration State**

Usage	Access	Data Type	Default	Min	Max	Semantics of Values

#### **Attributes**

**Guard Safety Attributes** 

**Guard Safety Status** 

**Attributes** 

**Hookup Test Configuration** 

<u>Attributes</u>

**Hookup Test Result** 

**Attributes** 

**Identify Motion Axis** 

**Attributes Based on Device** 

<u>Function Codes</u>

**Induction Motor Attributes** 

**Inertia Test Configuration** 

**Attributes** 

<u>Inertia Test Result</u>

<u>Attributes</u>

<u>Initialization Faults</u>

<u>Attributes</u>

<u>Interior Permanent Magnet</u>

Motor Attributes

<u>Linear PM Motor Attributes</u>

**Load Transmission and** 

Actuator Attributes

<u>Local Mode Configuration</u>

<u>Attribute</u>

Module/Node Fault and

<u>Alarm Attributes</u>

Motion Control Axis

Behavior Model

**Motion Control** 

**Configuration Attributes** 

Motion Control Interface

<u>Attributes</u>

**Motion Control Methods** 

**Motion Control Modes** 

Motion Control Signal

**Attributes** 

Motion Control Status

<u>Attributes</u>

Motion Database Storage

**Attributes** 

Motion Dynamic

**Configuration Attributes** 

**Motion Fault and Alarm** 

**Exceptions** 

**Motion Homing** 

**Configuration Attributes** 

Motion Instruction

Compatibility

Martin Black

<u>Motion Planner</u>

**Configuration Attributes** 

Motion Planner Output

Attributes

**Motor Attributes** 

N M = 4 = 1... A 44...; l= 1...4 = 1 = 1

		1		1		
Required - All	Get/	USINT	-	-	-	Enumeration
	GSV					0 = Axis Instance Created
						1 = Connection Created
						126 = Axis Inhibited
						128 = Axis Configured

State of the configuration state machine for this instance of the Motion Control Axis Object. The Axis Configuration State attribute is used for troubleshooting purposes to indicate where in the axis configuration state-machine this axis presently is. Even consumed and virtual axes will utilize this attribute. This attribute is valid for all physical and non-physical data types.

### **Axis State**

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - All	Get	USINT	-	-	-	Enumeration  0 = Ready  1 = Drive Enable, (direct drive control)  2 = Servo Control  3 = Faulted  4 = Shutdown  5 = Inhibited  6 = Ungrouped  7 = No Module
						8 = Configuring (FW default)

State of this instance of the Motion Control Axis. Indicates the operating state of the axis. Examples of possible states include: axis-ready, drive enable, servo control, axis faulted, axis shutdown, axis inhibited, and axis unassigned.

### Watch Event Task

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - E	Get	DINT	-	-	-	-

User Event Task that will be triggered to execute when a Watch event occurs.

This attribute is set through internal communication from the user Task object to the Axis object when the Task trigger attribute is set to select this attributes of an Axis. It cannot be set directly by an external device. It is available to be read externally for diagnostic information.

The Watch Event Task attribute indicates which user Task will be triggered when a watch event occurs. An instance value of 0 indicates that no event task has been configured to be triggered by the Watch Event.

The user Task is triggered at the same time that the Process Complete bit is set for the instruction that armed the watch event.

#### **IVIOTOR ATTRIBUTES IVIOGEI**

Motor Test Result

**Attributes** 

No Control Mode

**Position Control Mode** 

**Position Loop Signal** 

**Attributes** 

**Position Loop** 

**Configuration Attributes** 

Power and Thermal

**Management Configuration** 

<u>Attributes</u>

Power and Thermal

**Management Status** 

**Attributes** 

**Replicated Attributes** 

Required vs. Optional Axis

<u>Attributes</u>

Reset an APR Fault

**Rockwell Automation** 

Specific CIP Axis Alarm

<u>Names</u>

Rockwell Automation

**Specific Exceptions** 

**Rockwell Automation** 

Specific CIP Axis Fault

<u>Names</u>

**Rockwell Automation** 

**Specific Initialization Faults** 

Rockwell Automation

Specific Start Inhibits

Rotary PM Motor Attributes

Standard CIP Axis Fault and

**Alarm Names** 

**Standard Exceptions** 

Rotary PM Motor Attributes

**Standard Initialization** 

<u>Faults</u>

**Standard Start Inhibits** 

Start Inhibits Attributes

State Behavior

**Torque Control Mode** 

**Torque/Force Control** 

**Configuration Attributes** 

Torque/Force Control
Signal Attributes

Velocity Control Mode

<u>Velocity Loop Configuration</u>

**Attributes** 

<u>Velocity Loop Signal</u>

**Attributes** 

▶ Module Configuration Attributes

# Registration 1 Event Task

Usage	Access	Data Type	Default	Min	Мах	Semantics of Values
Required - E	Get	DINT	-	-	-	-

User Event Task that will be triggered to execute when a Registration 1 event occurs.

This attribute is set through internal communication from the user Task object to the Axis object when the Task trigger attribute is set to select this attributes of an Axis. It cannot be set directly by an external device. It is available to be read externally for diagnostic information.

The Registration 1 Event Task attribute indicates which user Task will be triggered when a Registration 1 event occurs. An instance value of 0 indicates that no event task has been configured to be triggered by the Registration 1 Event.

The user Task is triggered at the same time that the Process Complete bit is set for the instruction that armed the registration event.

# Registration 2 Event Task

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - E	Get	DINT	-	-	-	-

User Event Task that will be triggered to execute when a Registration 2 event occurs.

This attribute is set through internal communication from the user Task object to the Axis object when the Task trigger attribute is set to select this attributes of an Axis. It cannot be set directly by an external device. It is available to be read externally for diagnostic information.

The Registration 2 Event Task attribute indicates which user Task will be triggered when a Registration 2 event occurs. An instance value of 0 indicates that no event task has been configured to be triggered by the Registration 2 Event.

The user Task is triggered at the same time that the Process Complete bit is set for the instruction that armed the registration event.

### Home Event Task

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - E	Get	DINT	-	-	-	-

User Event Task that will be triggered to execute when a Home event occurs.

This attribute is set through internal communication from the user Task object to the Axis object when the Task trigger attribute is set to select this attributes of an Axis. It cannot be set directly by an external device. It is available to be read externally for diagnostic information.

The Home Event Task attribute indicates which user Task will be triggered when a home event occurs. An instance value of 0 indicates that no event task has been configured to be triggered by the Home Event.

The user Task is triggered at the same time that the Process Complete bit is set for the instruction that armed the home event.

### **Inhibit Axis**

#### **Bit Addressing**

**Common Attributes** 

**Data Conversions** 

Elementary data types

LINT data types

Floating Point Values

<u>Immediate values</u>

<u>Index Through Arrays</u>

Math Status Flags

Motion Error Codes (.ERR)

**Structures** 

- Equipment Sequence instructions
- ▶ Equipment Phase Instructions
- ▶ Alarm Instructions
- ▶ Advanced Math Instructions
- Array (File)/Shift Instructions
- ASCII Conversion Instructions
- ▶ ASCII Serial Port Instructions
- ▶ ASCII String Instructions
- **Bit Instructions** ■
- Compare Instructions
- Debug Instructions
- Drives Instructions
- Drive Safety Instructions
- For/Break Instructions
- ▶ Filter Instructions
- Function Block Attributes
- ▶ Compute/Math Instructions
- Move/Logical Instructions
- ▶ <u>Input/Output Instructions</u>
- Math Conversion Instructions
- ▶ Metal Form Instructions
- ▶ Motion Configuration Instructions
- Motion Event Instructions
- Motion Move Instructions
- ▶ Multi-Axis Coordinated Motion Instructions
- ▶ Program Control Instructions
- Sequencer Instructions
- ▶ Special Instructions
- Timer and Counter
  Instructions
- ▶ <u>Trigonometric Instructions</u>
- Process Control Instructions

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - All	Set/ SSV	SINT	0	-	-	0 triggers an uninhibit.  1 triggers an inhibit.  Setting to any non-zero value is treated the same as a value of 1, and results in the attribute being set to a 1.

Used to initiate putting an axis into the inhibit state.

This feature is designed for the following situations:

- To park an unused or faulted axis so that the application program can continue to run without the unused or faulted axis.
- To allow a 'generic' application program to be developed for a family of similar machines that may vary in axis count such that it can be configured during runtime to match the configuration of the specific machine.

The on-line inhibit process is an intrusive operation in that it impacts all axes associated to the same motion module as the one being inhibited. As such it is expected that the users will trigger this operation with the machine in a safe, non-operating, state. The inhibit process includes breaking connection to the associated motion module and then allowing the module to be reconfigured with or without (depending if you are inhibiting or un-inhibiting) this axis.

The inhibit/un-inhibit operation will also stop all motion on all axes associated to the same motion module including breaking all gearing relationships. This stop operation follows that of the shutdown fault action; servo action is immediately disabled as is the drives power structure. Unless some external form of braking capability is applied the axis will generally coast to a stop.

### Axis ID

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - All	Set/ GSV	DINT	-	-	-	ID

Unique number assigned to axis on creation by configuration software.

The Axis ID is used by the Absolute Position Recovery feature during a configuration software download to determine if a given axis is a new axis or pre-existing axis. If the axis existed prior to the download, the controller saves critical absolute position data associated with the axis before continuing the download. Using the Axis ID, the controller is able to match the saved absolute position data with the pre-existing axis and recover absolute position. Using the saved data, absolute position will be recomputed to account for any motion that occurred while the download was in process or while power was off.

# Axis Update Schedule

Usage	Access	Data Type	Default	Min	Max	Semantics of Values

- Sequential Function Chart (SFC) Instructions

- Studio 5000 Logix Designer Glossary

Required - All	Set/	USINT	-	-	-	Enumeration:
	GSV					0 = Base
						1 = Alternate 1
						2 = Alternate 2
						3-255 = Reserved

Determines the update schedule for the associated axis instance.

The default schedule setting of Base results in the axis being updated with every scan of Motion Task, or the Base Update Period of the Motion Group. Alternate 1 and Alternate 2 schedule selections result in the axis being updated at multiples of the Base Update Period given by the Alternate 1 and Alternate 2 Update Multiplier attribute values of the Motion Group, or Alternate 1 Update Period and Alternate 2 Update Period, respectively.

# Axis Data Type

Usage	Access	Data Type	Default	Min	Max	Semantics of Values
Required - All	GSV	USINT	-	-	-	Enumeration:
						0 = Feedback
						1 = Consumed
						2 = Virtual
						3 = Generic
						4 = Servo
						5 = Servo Drive
						6 = Generic Drive
						7 = CIP Drive

Associated tag data type for this instance of the Motion Control Axis Object.

The Axis Data Type attribute and is used to determine which data template, memory format, and set of attributes are created and applicable for this axis instance.

### See also

**CIP Axis Attributes** 

Motion Control Axis Behavior Model

Copyright © 2019 Rockwell Automation Technologies, Inc. All Rights Reserved.

How are we doing?